



Part II

1. Determine and classify all critical points of $f(x, y, z) = 2x^4 + y^2 + z^2 - xy^2 + x - 2z$.

Solution: The critical points of f are the solutions of the nonlinear system $\nabla f = 0$, that is

$$\begin{aligned} \nabla f = 0 &\Leftrightarrow \begin{cases} \frac{\partial f}{\partial x} = 0 \\ \frac{\partial f}{\partial y} = 0 \\ \frac{\partial f}{\partial z} = 0 \end{cases} \Leftrightarrow \begin{cases} 8x^3 - y^2 + 1 = 0 \\ 2y - 2xy = 0 \\ 2z - 2 = 0 \end{cases} \Leftrightarrow \begin{cases} 8x^3 - y^2 + 1 = 0 \\ 2y(1 - x) = 0 \\ z = 1 \end{cases} \\ &\Leftrightarrow \begin{cases} 8x^3 + 1 = 0 \\ y = 0 \\ z = 1 \end{cases} \vee \begin{cases} y^2 = 9 \\ x = 1 \\ z = 1 \end{cases} \Leftrightarrow \begin{cases} x = -\frac{1}{2} \\ y = 0 \\ z = 1 \end{cases} \vee \begin{cases} y = \pm 3 \\ x = 1 \\ z = 1 \end{cases} \end{aligned}$$

So, the critical points are: $(-\frac{1}{2}, 0, 1); (1, 3, 1); (1, -3, 1)$. They can be classified using the hessian matrix

$$H_f(x, y, z) = \begin{pmatrix} 24x^2 & -2y & 0 \\ -2y & (2 - 2x) & 0 \\ 0 & 0 & 2 \end{pmatrix}$$

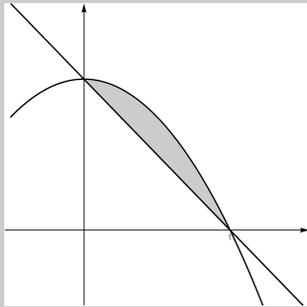
$$H_f(-\frac{1}{2}, 0, 1) = \begin{pmatrix} 6 & 0 & 0 \\ 0 & 3 & 0 \\ 0 & 0 & 2 \end{pmatrix}, \quad H_f(1, \pm 3, 1) = \begin{pmatrix} 24 & \mp 6 & 0 \\ \mp 6 & 0 & 0 \\ 0 & 0 & 2 \end{pmatrix}$$

For the point $(-\frac{1}{2}, 0, 1)$ we have $\Delta_1 = 6 > 0, \Delta_2 = 18 > 0, \Delta_3 = 36 > 0$ and so the point is a local minimum.

For the other points we have that $\Delta_1 = 24 > 0, \Delta_2 = -36 < 0, \Delta_3 = -72 < 0$, which means that the hessian matrix is indefinite and the points are saddle points.

2. Compute $\iint_{\Omega} x(y-1) dx dy$, where $\Omega = \{(x, y) \in \mathbb{R}^2 : x + y \geq 1, y \leq 1 - x^2, x \geq 0\}$.

Solution:



$$\begin{aligned} \iint_{\Omega} x(y-1) dx dy &= \int_0^1 \int_{1-x}^{1-x^2} x(y-1) dy dx \\ &= \int_0^1 x \left[\frac{(y-1)^2}{2} \right]_{y=1-x}^{y=1-x^2} dx \\ &= \int_0^1 \frac{x}{2} (x^4 - x^2) dx = \frac{1}{2} \left[\frac{x^6}{6} - \frac{x^4}{4} \right]_{x=0}^{x=1} = -\frac{1}{24} \end{aligned}$$

3. After certain economic considerations, it was possible to establish the following differential equation, for the dynamic equilibrium price of a given commodity.

$$y''(x) + a y'(x) + b y(x) = c,$$

where $y(x)$ is the price at time x and a, b, c are known constants.

- (a) Assuming that $a = 1$, $b = \frac{1}{2}$, $c = 1$, and $y(0) = y'(0) = 1$, determine the equilibrium price $y(x)$. Provide a long run estimate ($t \rightarrow +\infty$) of the equilibrium price.

Solution: Substituting all the given parameters in the differential equation, we get the initial value problem $y''(x) + y'(x) + \frac{1}{2}y(x) = 1, y(0) = y'(0) = 1$. Using the superposition principle, the general solution to this linear non-homogeneous equation can be obtained as $y(x) = y_h(x) + y_p(x)$, where $y_h(x)$ is the general of the homogeneous equation and $y_p(x)$ is a particular solution of the equation.

- i. **Solution of the homogeneous equation.** The characteristic polynomial is given by $P(D) = D^2 + D + \frac{1}{2}$ and has two complex roots, $-\frac{1}{2} \pm \frac{1}{2}i$. Hence we have

$$y_h(x) = e^{-\frac{x}{2}} \left(c_1 \cos \frac{x}{2} + c_2 \sin \frac{x}{2} \right).$$

- ii. **Particular solution of the equation.** Since the right hand side is a constant, we shall try a particular solution of the form $y_p(x) = k$, which leads to $y_p(x) = 2$.

iii. The **general solution** is then given by

$$y(x) = 2 + e^{-\frac{x}{2}} \left(c_1 \cos \frac{x}{2} + c_2 \sin \frac{x}{2} \right).$$

iv. Finally, the initial conditions must be imposed

$$\begin{cases} y(0) = 1 \\ y'(0) = 1 \end{cases} \Leftrightarrow \begin{cases} 2 + c_1 = 1 \\ -\frac{1}{2}c_1 + \frac{1}{2}c_2 = 1 \end{cases} \Leftrightarrow \begin{cases} c_1 = -1 \\ c_2 = 1 \end{cases}$$

yielding the particular solution

$$y(x) = 2 + e^{-\frac{x}{2}} \left(-\cos \frac{x}{2} + \sin \frac{x}{2} \right).$$

The long run behavior of the equilibrium price can be determined computing the limit

$$\lim_{x \rightarrow +\infty} y(x) = \lim_{x \rightarrow +\infty} \left[2 + e^{-\frac{x}{2}} \left(-\cos \frac{x}{2} + \sin \frac{x}{2} \right) \right] = 2.$$

(b) Show that if $a = 0$ and $b > 0$, the equilibrium price is a periodic function of x .

Solution: If $a = 0$ and $b > 0$ the characteristic polynomial, $P(D) = D^2 + b$ has two complex roots given by $\pm\sqrt{b}i$. The general solution is in this case given by (see previous calculations)

$$y(x) = \frac{c}{b} + c_1 \cos(\sqrt{b}x) + c_2 \sin(\sqrt{b}x),$$

which is a periodic function (with period $\frac{2\pi}{\sqrt{b}}$).

4. Suppose that the total income in a closed economy, denoted by Y_t , follows the difference equation $Y_t = 2Y_{t-1} - Y_{t-2} + G$, where G is a known constant.

(a) Set $Y_0 = Y_1 = 10$, $G = 2$ and determine the total income Y_t , for any $t \geq 2$.

Solution: This is a linear second order difference equation with constant coefficients, whose characteristic polynomial is $p(\lambda) = \lambda^2 - 2\lambda + 1 = (\lambda - 1)^2$. This polynomial has a real root ($\lambda = 1$) with multiplicity 2, so the general solution to the homogeneous equation is given by $Y_t^h = (c_1 t + c_2)1^t = c_1 t + c_2$. On the other hand, we must look for a particular solution of the form $y_t^* = kt^2$ (polynomials of degree 0 or 1 will not work as they are solutions to the ho-

mogeneous equation), which leads to the general solution $Y_t = c_1 t + c_2 + t^2$. Finally, using the initial conditions, we can compute the constants c_1, c_2

$$\begin{cases} Y_0 = 10 \\ Y_1 = 10 \end{cases} \Leftrightarrow \begin{cases} c_2 = 10 \\ c_1 + c_2 + 1 = 10 \end{cases} \Leftrightarrow \begin{cases} c_2 = 10 \\ c_1 = -1 \end{cases}$$

obtaining the particular solution $Y_t = t^2 - t + 10$.

(b) What should be the value of G for the total income to be linear in t ?

Solution: For general G , using the same procedure as above, the particular solution is given by $Y_t^* = \frac{G}{2}t^2$. Since the particular solution is the only non-linear component of the solution, setting $G = 0$ makes the solution linear in t .

Point values: 1. 3,0 2. 2,0 3. (a) 2,5 (b) 0,5 4. (a) 1.5 (b) 0.5



Part I

1. Classify the quadratic form $Q(x, y, z) = 4x^2 + 4xy + 2y^2 - 2yz + 2z^2$. Is there any vector $(a, b, c) \in \mathbb{R}^3$ such that $Q(a, b, c) = 0$? And such that $Q(a, b, c) < 0$? Justify.

Solution: The quadratic form is given by $Q(x, y, z) = (x, y, z)^T A(x, y, z)$, where

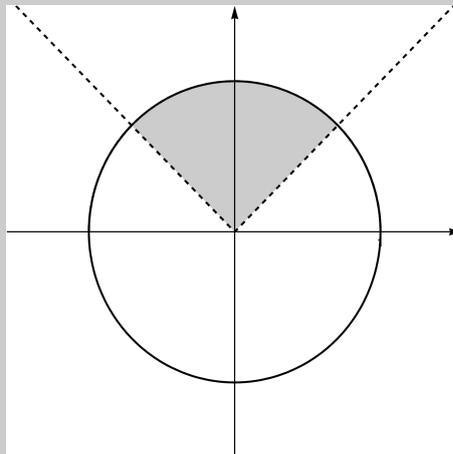
$$A = \begin{pmatrix} 4 & 2 & 0 \\ 2 & 2 & -1 \\ 0 & -1 & 2 \end{pmatrix}.$$

The determinants of the principal minors are $\Delta_1 = 4 > 0$, $\Delta_2 = 4 > 0$, $\Delta_3 = 4 > 0$. Since all these numbers are positive, the matrix is positive definite and so is the quadratic form. Taking $(a, b, c) = (0, 0, 0)$, we do have $Q(a, b, c) = 0$. Q being positive definite means that $Q(a, b, c) > 0, \forall (a, b, c) \neq (0, 0, 0)$ and so there is no vector (a, b, c) such that $Q(a, b, c) < 0$.

2. Consider the function $f : \mathbb{R}^2 \rightarrow \mathbb{R}$ defined by $f(x, y) = \ln(y - |x|) + \sqrt{1 - x^2 - y^2}$
- (a) Determine the domain of f , D_f , analytically and represent it graphically.

Solution:

$$D_f = \{(x, y) \in \mathbb{R}^2 : y - |x| > 0 \wedge 1 - x^2 - y^2 \geq 0\} = \{(x, y) \in \mathbb{R}^2 : y > |x| \wedge x^2 + y^2 \leq 1\}$$



- (b) Determine the interior and the boundary of D_f . Decide if D_f is open and if D_f is compact. Is Weierstrass's theorem applicable to f in D_f ? Is f bounded from below in D_f ? Justify.

Solution:

$$\text{Int}(D_f) = \{(x, y) \in \mathbb{R}^2 : y > |x| \wedge x^2 + y^2 < 1\}$$

$$\text{Bdy}(D_f) = \{(x, y) \in \mathbb{R}^2 : y = |x| \wedge x^2 + y^2 = 1\} \cup \{(x, y) \in \mathbb{R}^2 : y \geq |x| \wedge x^2 + y^2 = 1\}$$

$$\overline{D_f} = \text{Int}(D_f) \cup \text{Bdy}(D_f) = \{(x, y) \in \mathbb{R}^2 : y \geq |x| \wedge x^2 + y^2 \leq 1\}$$

Since $D_f \neq \text{Int}(D_f)$, the set is not open and since $D_f \neq \overline{D_f}$ the set is not closed and therefore not compact. Weierstrass's theorem is not applicable to f on D_f because D_f is not compact. Function f is not bounded from below on D_f because for example

$$\lim_{y \rightarrow 0^+} f(0, y) = \lim_{y \rightarrow 0^+} (\ln y + \sqrt{1 - y^2}) = -\infty,$$

which shows that f can take arbitrarily large negative values on D_f .

3. Let $f : \mathbb{R}^2 \rightarrow \mathbb{R}$ be given by

$$f(x, y) = \begin{cases} \frac{y^2 \sqrt{|x|}}{x^2 + y^2} & , (x, y) \neq (0, 0) \\ 0 & , x = y = 0 \end{cases}.$$

- (a) Compute the directional limits at $(0, 0)$.

Solution:

$$\lim_{\substack{(x,y) \rightarrow (0,0) \\ y=mx}} f(x, y) = \lim_{x \rightarrow 0} \frac{(mx)^2 \sqrt{|x|}}{x^2 + (mx)^2} = \lim_{x \rightarrow 0} \frac{m^2 \sqrt{|x|}}{1 + m^2} = 0.$$

- (b) Show that f is continuous in \mathbb{R}^2 .

Solution: If $(x, y) \neq (0, 0)$ the function is obviously continuous (quotient of continuous functions with nonzero denominator). If f is also continuous in $(0, 0)$, it will be continuous over \mathbb{R}^2 . From (a) we know that all directional limits at $(0, 0)$ are zero so the only possible candidate to limit is zero. Also, since

$$0 \leq \left| \frac{y^2 \sqrt{|x|}}{x^2 + y^2} - 0 \right| \leq \frac{(x^2 + y^2) \sqrt{|x|}}{x^2 + y^2} = \sqrt{|x|} \rightarrow 0 \quad (\text{as } (x, y) \rightarrow (0, 0)),$$

we can establish that $\lim_{(x,y) \rightarrow (0,0)} f(x, y) = 0 = f(0, 0)$, which allows us to conclude that f is continuous at $(0, 0)$ and therefore (as discussed above) over \mathbb{R}^2 .

(c) Compute the directional derivatives at $(0, 0)$.

Solution:

$$\begin{aligned}\frac{\partial f}{\partial(u, v)}(0, 0) &= \lim_{t \rightarrow 0} \frac{f(0 + ut, 0 + vt) - f(0, 0)}{t} = \lim_{t \rightarrow 0} \frac{v^2 t^2 \sqrt{|ut|}}{t((ut)^2 + (vt)^2)} \\ &= \lim_{t \rightarrow 0} \frac{v^2 \sqrt{|u|} \sqrt{|t|}}{u^2 + v^2} \frac{\sqrt{|t|}}{t} = \begin{cases} \infty, & v \neq 0 \\ 0, & v = 0 \end{cases}\end{aligned}$$

4. Suppose that the income (Y) is a function of capital and labor, $Y = K^{1/2}L^{1/2}$, and that both capital and labor are functions of time (t). Use the chain rule to compute $Y'(t)$, considering $K = t, L = t^2$.

Solution:

$$Y'(t) = \frac{\partial Y}{\partial K} \cdot \frac{dK}{dt} + \frac{\partial Y}{\partial L} \cdot \frac{dL}{dt} = \frac{L^{1/2}}{2K^{1/2}} \cdot 1 + \frac{K^{1/2}}{2L^{1/2}} \cdot 2t = \frac{t}{2\sqrt{t}} + \frac{2t\sqrt{t}}{2t} = \frac{3}{2}\sqrt{t}$$

5. Compute the second order Taylor polynomial of $f(x, y) = y^2 e^x$ around $(0, 0)$ and use it to estimate $f(0.1, 0.1)$

Solution: The second order Taylor polynomial is given by

$$\begin{aligned}p_2(x, y) &= f(0, 0) + \frac{\partial f}{\partial x}(0, 0)x + \frac{\partial f}{\partial y}(0, 0)y + \frac{1}{2!} \left(\frac{\partial^2 f}{\partial x^2}(0, 0)x^2 + 2 \frac{\partial^2 f}{\partial x \partial y}(0, 0)xy + \frac{\partial^2 f}{\partial y^2}(0, 0)y^2 \right) \\ &= \frac{1}{2!} 2y^2 = y^2.\end{aligned}$$

We can therefore consider the estimate $f(0.1, 0.1) \approx p_2(0.1, 0.1) = 0.1^2 = 0.01$.

Point values: 1. 1,5 2. (a) 1,5 (b) 1,5 3. (a) 1,0 (b) 1,5 (c) 1,0 4. 1,0 5. 1,0