## Computing derivatives

- Derivatives are a powerful tool in studying functions of one variable, providing a simple way of answering questions like: When is the function increasing? When is it decreasing? Where can it attain a maximum or a minimum?
- They measure the instantaneous rate of variation, the speed at witch a given function is changing in value.

$f^{\prime}(x)=\lim _{h \rightarrow 0} \frac{\overbrace{f(x+h)-f(x)}^{\text {Increase in } f}}{\underbrace{h}_{\text {Increase in } x}}$


## Partial derivatives

- When $f$ depends on more variables, it can be increasing in one direction but decreasing in another. The discussion of monotonicity must include a given direction.



## Partial derivatives

Consider $f: \mathbb{R}^{2} \rightarrow \mathbb{R}$ and suppose we want to evaluate the increase in the value of $f$ when we move away from $(x, y)$, in the $x$-direction or in the $y$-direction. If we move $h$, the mean rate of variation is given by


The instantaneous rate of variation with respect to $x$ is defined as

$$
\lim _{h \rightarrow 0} \frac{f(x+h, y)-f(x, y)}{h}
$$

Increase in $f$


Increase in $x$

The instantaneous rate of variation with respect to $y$ is defined as

$$
\lim _{h \rightarrow 0} \frac{f(x, y+h)-f(x, y)}{h}
$$

- The partial derivative with respect to $x$ is defined as the instantaneous rate of variation with respect to $x$ and is denoted by

$$
\frac{\partial f}{\partial x}(x, y)=\lim _{h \rightarrow 0} \frac{f(x+h, y)-f(x, y)}{h}
$$

- The partial derivative with respect to $y$ is defined as the instantaneous rate of variation with respect to $y$ and is denoted by

$$
\frac{\partial f}{\partial y}(x, y)=\lim _{h \rightarrow 0} \frac{f(x, y+h)-f(x, y)}{h}
$$

## Definition (partial derivative)

Let $f: \Omega \subset \mathbb{R}^{n} \rightarrow \mathbb{R}$ and $a \in \operatorname{int}(\Omega)$. The partial derivative of $f$ with respect to $x_{i}$ at $a$ is denoted by $f_{x_{i}}^{\prime}(a)$ or $\frac{\partial f}{\partial x_{i}}(a)$ and is defined as

$$
f_{x_{i}}^{\prime}(a)=\lim _{h \rightarrow 0} \frac{f(x_{1}, \cdots, \overbrace{x_{i}+h}^{i^{t h}}, \cdots, x_{n})-f\left(x_{1}, \cdots, x_{i}, \cdots, x_{n}\right)}{h}
$$

If we fix $x_{k}=a_{k}$ for $k \neq i$, we can define the real function $x \mapsto \psi_{i}(x)=f(a_{1}, \cdots, \underbrace{x}_{i^{\text {th }}}, \cdots, a_{n})$, and we have that

$$
\frac{\partial f}{\partial x_{i}}\left(a_{1}, \cdots, a_{n}\right)=\psi_{i}^{\prime}\left(a_{i}\right)
$$

## Example

Consider $f\left(x_{1}, x_{2}\right)=x_{1}^{2}+x_{2}^{2}$. If we want to compute the partial derivatives at $(1,2)$ we need only consider the partial functions

$$
\begin{aligned}
\psi_{1}\left(x_{1}\right)=f\left(x_{1}, 2\right)=x_{1}^{2}+4, & \psi_{2}\left(x_{2}\right)=f\left(1, x_{2}\right)=1+x_{2}^{2} \\
\psi_{1}^{\prime}\left(x_{1}\right)=2 x_{1}, & \psi_{2}^{\prime}\left(x_{2}\right)=2 x_{2} \\
\frac{\partial f}{\partial x_{1}}(1,2)=\psi_{1}^{\prime}(1)=2, & \frac{\partial f}{\partial x_{2}}(1,2)=\psi_{2}^{\prime}(2)=4
\end{aligned}
$$

From the practical point of view:

- We compute $f_{x_{1}}^{\prime}$ considering $x_{2}$ as a constant and computing the usual derivative using $x_{1}$ as the variable.
- We compute $f_{x_{2}}^{\prime}$ considering $x_{1}$ as a constant and computing the usual derivative using $x_{2}$ as the variable.


## Example

Let $f(x, y, z)=x^{2} y+y^{2} z+\sin \left(x^{2}+y^{3}+z^{4}\right)$. Then

$$
\begin{aligned}
\frac{\partial f}{\partial x} & =\left(x^{2} y\right)_{x}^{\prime}+\left(y^{2} z\right)_{x}^{\prime}+\left(x^{2}+y^{3}+z^{4}\right)_{x}^{\prime} \cos \left(x^{2}+y^{3}+z^{4}\right) \\
& =2 x y+2 x \cos \left(x^{2}+y^{3}+z^{4}\right) \\
\frac{\partial f}{\partial y} & =\left(x^{2} y\right)_{y}^{\prime}+\left(y^{2} z\right)_{y}^{\prime}+\left(x^{2}+y^{3}+z^{4}\right)_{y}^{\prime} \cos \left(x^{2}+y^{3}+z^{4}\right) \\
& =x^{2}+2 y z+3 y^{2} \cos \left(x^{2}+y^{3}+z^{4}\right) \\
\frac{\partial f}{\partial z} & =\left(x^{2} y\right)_{z}^{\prime}+\left(y^{2} z\right)_{z}^{\prime}+\left(x^{2}+y^{3}+z^{4}\right)_{z}^{\prime} \cos \left(x^{2}+y^{3}+z^{4}\right) \\
& =y^{2}+4 z^{3} \cos \left(x^{2}+y^{3}+z^{4}\right)
\end{aligned}
$$

## Example

$$
f(x, y)= \begin{cases}2 y+\frac{x^{2} y^{2}}{x^{2}+y^{2}} & ,(x, y) \neq(0,0) \\ 0 & , x=y=0\end{cases}
$$

- If we want to compute the partial derivatives at $(0,0)$ we must use the definition, because $f$ is defined by more then one expression in any neighborhood of $(0,0)$.
- If we want to compute the partial derivatives at any other point $(x, y) \neq(0,0)$ we can use the usual rules for derivatives.

$$
\begin{aligned}
& \frac{\partial f}{\partial x}(0,0)=\lim _{h \rightarrow 0} \frac{f(0+h, 0)-f(0,0)}{h}=\lim _{h \rightarrow 0} \frac{0-0}{h}=0 \\
& \frac{\partial f}{\partial y}(0,0)=\lim _{h \rightarrow 0} \frac{f(0,0+h)-f(0,0)}{h}=\lim _{h \rightarrow 0} \frac{2 h-0}{h}=2
\end{aligned}
$$

## Example (cont.)

For any $(x, y) \neq(0,0)$ we have that

$$
\begin{aligned}
\frac{\partial f}{\partial x} & =0+\frac{\left(x^{2} y^{2}\right)_{x}^{\prime}\left(x^{2}+y^{2}\right)-\left(x^{2} y^{2}\right)\left(x^{2}+y^{2}\right)_{x}^{\prime}}{\left(x^{2}+y^{2}\right)^{2}} \\
& =\frac{2 x y^{2}\left(x^{2}+y^{2}\right)-x^{2} y^{2} 2 x}{\left.\left(x^{2}+y^{2}\right)^{2}\right)}=\frac{2 x y^{4}}{\left(x^{2}+y^{2}\right)^{2}} \\
\frac{\partial f}{\partial y} & =(2 y)_{y}^{\prime}+\frac{\left(x^{2} y^{2}\right)_{y}^{\prime}\left(x^{2}+y^{2}\right)-\left(x^{2} y^{2}\right)\left(x^{2}+y^{2}\right)_{y}^{\prime}}{\left(x^{2}+y^{2}\right)^{2}} \\
& =2+\frac{2 x^{2} y\left(x^{2}+y^{2}\right)-x^{2} y^{2} 2 y}{\left.\left(x^{2}+y^{2}\right)^{2}\right)}=2+\frac{2 x^{4} y}{\left(x^{2}+y^{2}\right)^{2}}
\end{aligned}
$$

We can substitute $x, y$ in these expressions and get the values of the partial derivatives, in any point except ( 0,0 ).

## Example (cont.)

Finalmente,

$$
\begin{gathered}
\frac{\partial f}{\partial x}(x, y)=\left\{\begin{array}{cl}
\frac{2 x y^{4}}{\left(x^{2}+y^{2}\right)^{2}} & ,(x, y) \neq(0,0) \\
0 & ,(x, y)=(0,0)
\end{array}\right. \\
\frac{\partial f}{\partial y}(x, y)=\left\{\begin{array}{cl}
2+\frac{2 x^{4} y}{\left(x^{2}+y^{2}\right)^{2}} & ,(x, y) \neq(0,0) \\
2 & ,(x, y)=(0,0)
\end{array}\right.
\end{gathered}
$$

- Unlike what happens for functions of one variable, the existence of partial derivatives does not imply the continuity of a function $f: \mathbb{R}^{n} \rightarrow \mathbb{R}$. For example

$$
f(x, y)= \begin{cases}1 & , \text { se } x y=0 \\ 0 & , \text { se } x y \neq 0\end{cases}
$$

is obviously discontinuous at $(0,0)$ but both partial derivatives exist and are equal to zero.

- This fact indicates that the concept of partial derivative is probably not the best extension of the concept of differentiability.


## Directional derivatives

The partial derivatives measure the rate of variation of a given function in the direction of the coordinate axis. One possible extension is to assess the rate of variation in the direction of a given vector $\boldsymbol{v}$.

## Definition

Let $\Omega \subset \mathbb{R}^{n}$ be an open set, $f: \Omega \rightarrow \mathbb{R}, \boldsymbol{a} \in \Omega$ and $\boldsymbol{v} \in \mathbb{R} \backslash\{0\}$. The derivative of $f$ along $\boldsymbol{v}$ is defined by the limit

$$
\begin{aligned}
\partial_{\boldsymbol{v}} f(\boldsymbol{a}) & =\lim _{h \rightarrow 0} \frac{f(\boldsymbol{a}+t \boldsymbol{v})-f(\boldsymbol{a})}{h} \\
& =\lim _{h \rightarrow 0} \frac{f\left(a_{1}+h v_{1}, \cdots, a_{n}+h v_{n}\right)-f\left(a_{1}, \cdots, a_{n}\right)}{h} .
\end{aligned}
$$

If $\|\boldsymbol{v}\|=1$ we call this the directional derivative of $f$ along $\boldsymbol{v}$.

## Example

Compute all directional derivatives of $f$ at $(0,0)$, where

$$
\begin{gathered}
f(x, y)=\left\{\begin{array}{cl}
\frac{x y^{2}}{x^{2}+y^{4}} & ,(x, y) \neq(0,0) \\
0 & , x=y=0
\end{array}\right. \\
\partial_{v} f(0,0)=\lim _{h \rightarrow 0} \frac{f\left(0+h v_{1}, 0+h v_{2}\right)-f(0,0)}{h} \\
=\lim _{h \rightarrow 0} \frac{\frac{h v_{1}\left(h v_{2}\right)^{2}}{\left(h v_{1}\right)^{2}+\left(h v_{2}\right)^{4}}-0}{h}=\lim _{h \rightarrow 0} \frac{v_{1} v_{2}^{2}}{v_{1}^{2}+h^{2} v_{2}^{4}} \\
= \begin{cases}0, & v_{1}=0 \\
\frac{v_{2}^{2}}{v_{1}}, & v_{1} \neq 0\end{cases}
\end{gathered}
$$

## Example (cont.)

If easy to check that $f$ is not continuous at $(0,0)$. The existence of all directional derivatives is not enough to guarantee that a function is continuous.

## Remark

The partial derivatives are a particular case of directional derivatives, in fact

$$
\frac{\partial f}{\partial x_{i}}=\partial_{e_{i}} f
$$

For example, if $f: \mathbb{R}^{2} \rightarrow \mathbb{R}$, we have that

$$
\frac{\partial f}{\partial x}(x, y)=\partial_{(1,0)} f(x, y), \quad \frac{\partial f}{\partial y}(x, y)=\partial_{(0,1)} f(x, y)
$$

## Differentiability

For functions of one variable we say that $f$ has derivative at $a$ or that $f$ is differentiable at $a$ if the following limit exists:

$$
\lim _{h \rightarrow 0} \frac{f(a+h)-f(a)}{h} \stackrel{\text { def }}{=} f^{\prime}(a)
$$

This is equivalent to say that there exists a constant, that we call $f^{\prime}(a)$, such that

$$
\lim _{h \rightarrow 0} \frac{f(a+h)-f(a)-f^{\prime}(a) h}{h}=0
$$

This means that the increments of $f$ are "well" explained by the linear function $D f(h)=f^{\prime}(a) h$.


## Differentiability

## Definition

Let $\Omega \subset \mathbb{R}^{n}$ be an open set, $f: \Omega \rightarrow \mathbb{R}$ and $\boldsymbol{a} \in \Omega$ such that $B_{\delta}(\boldsymbol{a}) \subset \Omega$. We say that $f$ is differentiable at $\boldsymbol{a}$ if there exists a linear aplication $D_{1}: \mathbb{R}^{n} \rightarrow \mathbb{R}$ such that, for all $\boldsymbol{h}$ with $\|\boldsymbol{h}\|<\delta$ such that

$$
f(\boldsymbol{a}+\boldsymbol{h})-f(\boldsymbol{a})=D_{1}(\boldsymbol{h})+\mathcal{E}(\boldsymbol{h})\|\boldsymbol{h}\|,
$$

where $\lim _{\boldsymbol{h} \rightarrow 0} \mathcal{E}(\boldsymbol{h})=0$.

## Remark

We can say, equivalentlly, that $f$ is differentiable at $\boldsymbol{a}$ iif

$$
\lim _{\boldsymbol{h} \rightarrow 0} \frac{f(\boldsymbol{a}+\boldsymbol{h})-f(\boldsymbol{a})-D_{1}(\boldsymbol{h})}{\|\boldsymbol{h}\|}=0
$$

## Proposition

If $f$ is differentiable at $\boldsymbol{a}$ all directional derivatives exist at $\boldsymbol{a}$, and we have

$$
D_{1}(\boldsymbol{v})=\partial_{\boldsymbol{v}} f(\boldsymbol{a})
$$

In particular, all partial derivatives exist at $\boldsymbol{a}$ and

$$
D_{1}(\boldsymbol{h})=h_{1} \frac{\partial f}{\partial x_{1}}(\boldsymbol{a})+\cdots+h_{n} \frac{\partial f}{\partial x_{n}}(\boldsymbol{a})
$$

## Definition

The linear application introduced above is called the first order differential of $f$ at $\boldsymbol{a}$, and is denoted by

$$
D f(\boldsymbol{a})(\boldsymbol{h})=h_{1} \frac{\partial f}{\partial x_{1}}(\boldsymbol{a})+\cdots+h_{n} \frac{\partial f}{\partial x_{n}}(\boldsymbol{a})
$$

## Differentiability

Considering the previous results we can rewrite the definition of Differentiability as follows:

## Definition (Differentiability)

Let $\Omega \subset \mathbb{R}^{n}$ be an open set, $f: \Omega \rightarrow \mathbb{R}$ and $\boldsymbol{a} \in \Omega$. Se say that $f$ is differentiable at $\boldsymbol{a}$ if

$$
\frac{f(\boldsymbol{a}+\boldsymbol{h})-f(\boldsymbol{a})-\sum_{i=1}^{n} h_{i} \frac{\partial f}{\partial x_{i}}(\boldsymbol{a})}{\|\boldsymbol{h}\|}=0 .
$$

## Example

The function $f(x, y)=x y$ is differentiable at any point $\left(a_{1}, a_{2}\right) \in \mathbb{R}^{2}$. To check this we only need to evaluate the limit

$$
\begin{gathered}
\lim _{\left(h_{1}, h_{2}\right) \rightarrow(0,0)} \frac{f(\boldsymbol{a}+\boldsymbol{h})-f(\boldsymbol{a})-h_{1} f_{x}^{\prime}(\boldsymbol{a})-h_{2} f_{y}^{\prime}(\boldsymbol{a})}{\sqrt{h_{1}^{2}+h_{2}^{2}}}= \\
\lim _{\left(h_{1}, h_{2}\right) \rightarrow(0,0)} \frac{\left(a_{1}+h_{1}\right)\left(a_{2}+h_{2}\right)-a_{1} a_{2}-a_{2} h_{1}-a_{1} h_{2}}{\sqrt{h_{1}^{2}+h_{2}^{2}}}= \\
\lim _{\left(h_{1}, h_{2}\right) \rightarrow(0,0)} \frac{a_{1} \theta_{2}+a_{1} k_{2}+h_{1+2}+h_{1} h_{2}-a_{1} \theta_{2}-a_{2} k_{1}-a_{1} k_{2}}{\sqrt{h_{1}^{2}+h_{2}^{2}}}= \\
\lim _{\left(h_{1}, h_{2}\right) \rightarrow(0,0)} \frac{h_{1} h_{2}}{\sqrt{h_{1}^{2}+h_{2}^{2}}}:=L
\end{gathered}
$$

## Example (cont.)

Now, two situations can occur:

- If $L$ exists and is equal to zero, $f$ is differentiable.
- If $L$ does not exist or exists but it is not zero, the function in not differentiable.

In this case we can see that

$$
\begin{aligned}
\left|\frac{h_{1} h_{2}}{\sqrt{h_{1}^{2}+h_{2}^{2}}}\right| & =\frac{\left|h_{1}\right|\left|h_{2}\right|}{\sqrt{h_{1}^{2}+h_{1}^{2}}} \leq \frac{\sqrt{h_{1}^{2}+h_{1}^{2}} \cdot \sqrt{h_{1}^{2}+h_{1}^{2}}}{\sqrt{h_{1}^{2}+h_{1}^{2}}} \\
& =\sqrt{h_{1}^{2}+h_{1}^{2}} \xrightarrow{\left(h_{1}, h_{2} \rightarrow 0\right)} 0
\end{aligned}
$$

And so $f$ is differentiable at any point $\left(a_{1}, a_{2}\right) \in \mathbb{R}^{2}$.

## Proposition

Let $\Omega \subset \mathbb{R}^{n}$ be an open set, $f: \Omega \rightarrow \mathbb{R}$ and $\boldsymbol{a} \in \Omega$. If all partial derivatives exist at $\boldsymbol{a}$ and are continuous in a neighborhood of $\boldsymbol{a}$, then $f$ is differentiable at $\boldsymbol{a}$.

## Proposition

Let $\Omega \subset \mathbb{R}^{n}$ be an open set, $f: \Omega \rightarrow \mathbb{R}$ and $\boldsymbol{a} \in \Omega$. If $f$ is differentiable at a then
i. $f$ is continuous at $\boldsymbol{a}$.
ii. all partial derivatives exist at a.
iii. All directional derivatives exist at $\boldsymbol{a}$.
iv. $\partial_{\boldsymbol{v}} f(\boldsymbol{a})=h_{1} \frac{\partial f}{\partial x_{1}}(\boldsymbol{a})+\cdots+h_{n} \frac{\partial f}{\partial x_{n}}(\boldsymbol{a})$.

