

MICROECONOMETRICS II

2018/19

Framework

Course description:

- Addresses complementary topics relative to Microeconometrics
- Focus on **cross-sectional** and **panel data**:
 - The interaction between theory and empirical econometric analysis is emphasized
 - Students will be trained in formulating and testing economic models using real data

Pre-requisites: Econometrics, Microeconometrics I

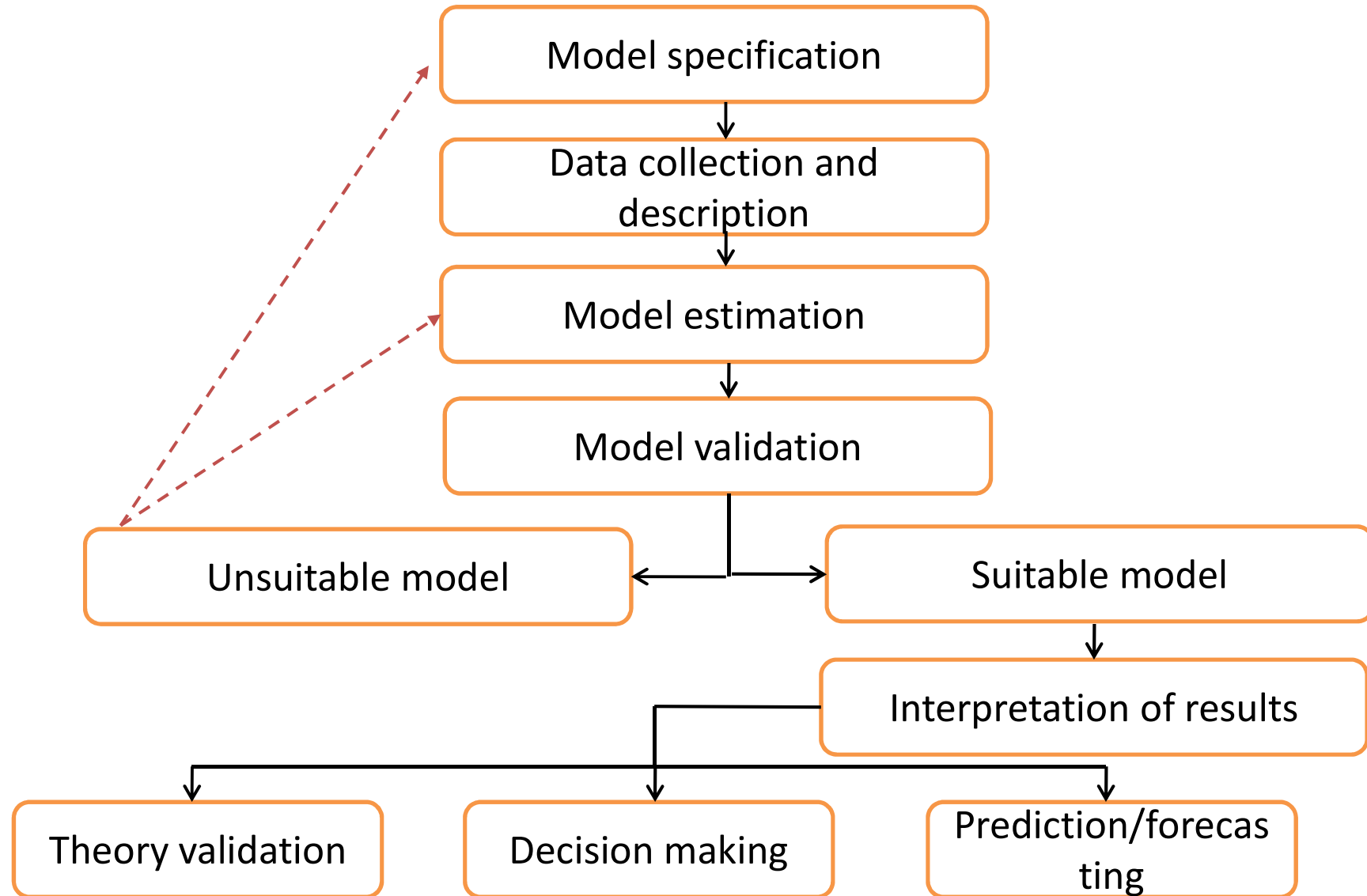
Basic reference: Cameron A.C. e Trivedi P.K. (2005), Microeconometrics, Methods and Applications, Cambridge

Framework

List of topics:

- Estimation and inference in nonlinear models: extremum estimators, GMM estimators, maximum likelihood estimators
- Models for count data or positive dependent variable
- Models for fractional data
- Models for truncated, censored, excess of zeros, or with endogenous stratification data
- Models for duration data
- Quantile regression

Methodology



Main types of microeconomic models

- Regression Model: explaining $E(Y|X)$
- Probabilistic model:
 - Aim: Explaining $P(Y|X)$
 - Usually incorporates a regression model for $E(Y|X)$ e $P(Y|X)$

Y : dependent variable

X : explanatory variables

$E(Y|X)$: expected value for Y given X

$P(Y|X)$: probability of Y being equal to a specific value given X

Dependent Variable versus Econometric Model

The numeric characteristics of the dependent variable restricts the variants that may be applied in each case:

Y	Type of outcome	Main model
$] -\infty, +\infty[$	Unbounded data	Linear
$\{0,1\}$	Binary choices	Logit,...
$\{0,1,2, \dots, J - 1\}$	Multinomial choices	Multinomial logit,...
$\{0,1,2, \dots, J - 1\}$	Ordered choices	Ordered logit,...
$\{0,1,2, \dots\}$	Count data	Poisson,...
$[0, +\infty[$	Nonnegative data	Exponential
$[0,1]$	Fractional data	Fractional Logit,...

Quantities of interest in nonlinear models

- Partial effects over

- $E(Y|X) = G(X\beta)$

- $P(Y|X) = F(X\beta)$

- Effects: $\Delta X_j = 1 \Rightarrow$

- $\Delta E(Y|X) = \frac{\partial E(Y|X)}{\partial X_j} = \frac{\partial G(X\beta)}{\partial X_j} = \beta_j \frac{\partial G(X\beta)}{\partial X\beta} = \beta_j g(x_i'\beta)$

- $\Delta P(Y|X) = \frac{\partial P(Y|X)}{\partial X_j} = \frac{\partial F(X\beta)}{\partial X_j} = \beta_j \frac{\partial F(X\beta)}{\partial X\beta} = \beta_j f(x_i'\beta)$

- Other quantities of interest

- Example: when modelling a nonnegative outcome, $Y \geq 0$, with lots of zeros, it may be interesting to estimate also:

- » $P(Y = 0|X)$

- » $E(Y|X, Y > 0)$

Model Transformations and Adaptations

Bounded continuous outcomes may often be transformed in such a way that they give rise to unbounded outcomes which may be modelled using a linear model

Any microeconomic model may require adaptations:

- Data structure: cross-section, panel
- Non-random samples: stratified, censored, truncated
- Measurement error
- Endogenous explanatory variables
- Corner solutions / excess of zeros

Types of Explanatory Variables

Quantitative variables:

- Levels (Euro, kilograms, meters,...)
- Levels and squares
- Logs
- Growth rates
- Per capita values

Qualitative variables

- Binary (dummy) variables:

$$X = \{0,1\}$$

- Interaction variables:

$$X = \textit{Dummy var.} * (\textit{Quantitative or dummy var.})$$

Extremum estimators

An extremum estimator $\hat{\theta}$ maximizes or minimizes a given objective function, defined as a function of a sample of $i=1, \dots, n$ individuals with data on $Z = (Y, X)$ and the k -dimensioned vector of parameters θ :

$$\theta = \underset{\theta \in \Theta}{\operatorname{argmax}} Q_n(\theta)$$

The estimator $\hat{\theta}$ is the solution of the first order condition

$$\nabla_{\theta} Q_n(\theta) \Big|_{\theta = \hat{\theta}} = 0$$

Extremum estimators

Particular cases:

1. M Estimators: maximum likelihood like

$$Q_n(\theta) = \frac{1}{n} \sum_{i=1}^n q(z_i, \theta)$$

2. GMM: minimize a quadratic form of averages of moment conditions

$$Q_n(\theta) = -g_n \widehat{W} g_n$$

where $g_n = \frac{1}{n} \sum_{i=1}^n g(z_i, \theta)$ reflect s , $s \geq k$, moment conditions $E[g(z, \theta_0,)] = 0$ and W is a weighing matrix

- $W=I$ in just-identified cases ($s=k$)

Extremum estimators

Particular cases:

3. OLS estimator: $Q_n(\theta) = \frac{1}{n} \sum_{i=1}^n [y_i - x\theta]^2$

4. NLS estimator: $Q_n(\theta) = \frac{1}{n} \sum_{i=1}^n [y_i - h(x, \theta)]^2$, where $h(\cdot)$ is a nonlinear function

5. ML estimator: $Q_n(\theta) = \frac{1}{n} \sum_{i=1}^n \ln f(x_i, \theta)$, where $f(\cdot)$ is the pdf assumed

OLS, NLS, and ML estimators are particular cases of both M and GMM estimators, with $W=I$ and first order conditions used as moment conditions

Extremum estimators

Particular cases:

6. LAD (least absolute deviation) estimator

$$Q_n(\theta) = \frac{1}{n} \sum_{i=1}^n |y_i - \text{med}(Y|X)|$$

7. Manski's maximum score estimator (binary models)

$$Q_n(\theta) = -\frac{1}{n} \sum_{i=1}^n |y_i - 1(x\theta > 0)|$$

where $1(\cdot)$ is an indicator function

GMM estimators

According to Newey and McFadden (1994)

1. Consistency - Theorem 2.6 - under the established regularity conditions, the GMM estimator $\hat{\theta}$ converges to the true value θ_0

$$plim\hat{\theta} = \theta_0$$

2. Asymptotic normality - Theorem 3.4

$$\sqrt{n}(\hat{\theta} - \theta_0) \xrightarrow{d} N[0, (A'WA)^{-1}A'WBWA(A'WA)^{-1}]$$

where $A = E[\nabla_{\theta} g(z, \theta_0)]$ and $B = E[g(z, \theta_0)g(z, \theta_0)']$

GMM estimators

3. Asymptotic efficiency - Theorem 5.2 – assuming B as a nonsingular matrix, the GMM estimator with $W = \text{plim}\hat{W} = B^{-1}$ is asymptotically efficient within the class of GMM estimators.

- In this case, the following simplification is obtained

$$\sqrt{n}(\hat{\theta} - \theta_0) \xrightarrow{d} N[0, (A' B^{-1} A)^{-1}]$$

- If, additionally, we have exact identification (s=k: same number of parameters to estimate and moment conditions):

$$\sqrt{n}(\hat{\theta} - \theta_0) \xrightarrow{d} N[0, A^{-1} B A'^{-1}]$$

- Estimator of the covariance matrix \hat{C}_n : replace A and B by A_n and B_n , which result from the replacement of $E(\cdot)$ by $\frac{1}{n} \sum_{i=1}^n$.

GMM estimators

Alternative forms of the weighting matrix W :

Different GMM estimators result from different forms of W

- **Two-step:**
 - Use $W = I$ and estimate $\hat{\theta}_{1step}$
 - Use $\hat{\theta}_{1step}$ in W and then estimate $\hat{\theta}_{2step}$
- **Iterated:** repeats two-step ($\hat{\theta}_{2step}$ is used to compute W of a 3rd step, $\hat{\theta}_{3step}$ is used to compute the W of a 4rd step, ...)
- **Continuously updating GMM:** in each step, $\hat{\theta}$ is estimated from both from the moment conditions and W , which is designated as $W(\theta)$

ML and QML estimators

Review...

Requirement: specification of

- The G function in $E(Y|X) = G(X\beta)$
- The F function in $Pr(Y|X) = F(X\beta)$

Main assumptions:

- ML:
 - Correct specification of both G and F
- QML:
 - Correct specification of G
 - F does not need to be correctly specified but needs to be included in the linear exponential family (e.g. Normal, Bernoulli, Poisson, Exponential, Gama, etc.)

ML and QML estimators

ML / QML estimation:

- Density function: $f(y_i|x_i; \theta)$
- Likelihood function:
 - Gives the probability for the occurrence of a full set of sample values on the assumption that the density function $f(y_i|x_i; \theta)$ is correct
 - Assuming independence, it is calculated as

$$L = \prod_{i=1}^n f(y_i|x_i; \theta)$$

ML and QML estimators

- The parameter θ is unknown and its value is chosen in order to maximize L and thus to maximize the probability that the sample values were in fact generated by the chosen density $f(\cdot)$:

$$\max_{\theta} L = \prod_{i=1}^n f(y_i | x_i; \theta)$$

- Actually, it is more common to maximize $LL = \ln(L)$:

$$\max_{\theta} LL = \sum_{i=1}^n \ln[f(y_i | x_i; \theta)]$$

- It is easier to maximize
- It produces the same estimates for θ

ML and QML estimators

Quantities to take into account:

- Score vector: $S(\theta) = \nabla_{\theta} \ln[f(y|x; \theta)]$
- Hessian matrix: $H(\theta) = \nabla_{\theta\theta} \ln[f(y|x; \theta)]$
- Symmetric of the expected hessian matrix: $A = E[-H(\theta)]$
- Fisher information matrix: $\mathcal{I} = B = E[S(\theta)S(\theta)']$
- Information matrix equality: $\mathcal{I} = E[H(\theta)]$ or $B = -A$

ML and QML estimators

Properties of ML estimators:

- Consistency - Theorem 2.5: $\text{plim}\hat{\theta} = \theta_0$
- Asymptotic normality - Theorem 3.3: $\sqrt{n}(\hat{\theta} - \theta_0) \xrightarrow{d} N[0, \mathcal{F}^{-1}]$,
which results from $\sqrt{n}(\hat{\theta} - \theta_0) \xrightarrow{d} N[0, A^{-1}BA'^{-1}]$ with $B=-A$
- Asymptotic efficiency - Theorem 5.1: this theorem refers to GMM, but establishes \mathcal{F}^{-1} as the inferior limit of the GMM covariance matrix, which is the ML covariance matrix.

ML and QML estimators

Properties of QML estimators:

- Consistency : $\text{plim}\hat{\theta} = \theta_0$
- Asymptotic normality: $\sqrt{n}(\hat{\theta} - \theta_0) \xrightarrow{d} N[0, A^{-1}BA'^{-1}]$ (since the Fisher information matrix equality does not hold (correspond to a GMM estimator with exact identification))
- Asymptotic efficiency requires the additional assumption of the correct specification of $V(Y|X)$. In these conditions $A = -A$, which implies the simplification of $A^{-1}BA'^{-1}$ the ML result \mathcal{J}^{-1}

* In ML estimators, the designated robust covariance matrix $A^{-1}BA'^{-1}$ may be used instead of the standard form \mathcal{J}^{-1} .

Additional alternatives: cluster-robust (panel data) and bootstrap

GMM hypothesis testing

1. Wald, LM, and LR tests

Define r restrictions $r(\theta) = 0$ with $R(\theta) = \nabla_{\theta} r(\theta)$ and denote the estimators of the restricted and unrestricted model as θ_r and θ_u , respectively

Theorem 9.2: all the following test statistics converge in distribution to χ_r^2 :

$$\begin{aligned}W &= nr(\hat{\theta}_u)'[\hat{R}\hat{C}^{-1}\hat{R}']r(\hat{\theta}_u) \\LM &= n\nabla_{\theta}Q_n(\hat{\theta}_r)'\hat{B}^{-1}\hat{A}\hat{C}\hat{A}'\hat{B}^{-1}\nabla_{\theta}Q_n(\hat{\theta}_r) \\LR &= n[Q_n(\hat{\theta}_r) - Q_n(\hat{\theta}_u)]\end{aligned}$$

where \hat{C} is the covariance matrix estimator

GMM hypothesis testing

Particular case: ML

$$\begin{aligned}W &= nr(\hat{\theta}_u)'[\hat{R}\hat{C}^{-1}\hat{R}']r(\hat{\theta}_u) \\LM &= n\nabla_{\theta}LL(\hat{\theta}_r)'\hat{C}\nabla_{\theta}LL(\hat{\theta}_r) \\LR &= n[LL(\hat{\theta}_r) - LL(\hat{\theta}_u)]\end{aligned}$$

where \hat{C} is the estimator of the information matrix

GMM hypothesis testing

Particular case: ML

- Test for the joint significance of a set of parameters: LR test
 - Restricted model: $Pr(Y|X) = F(\theta_{r0} + \theta_{r1}x_1 + \dots + \theta_{rg}x_g)$
 - Full model: $Pr(Y|X) = F(\theta_0 + \theta_1x_1 + \dots + \theta_gx_g + \theta_{g+1}x_{g+1} + \dots + \theta_kx_k)$
 - Hypothesis in test:
 - $H_0: \theta_{g+1} = \dots = \theta_k = 0$ (restricted model)
 - $H_1: \text{No } H_0$ (full model)
- Both the restricted and unrestricted models have to be estimated

GMM hypothesis testing

Particular case: ML

- Test for individual significance: Wald test
 - In general

$$W = \hat{\theta}'_F [\text{Var}(\hat{\theta}_r)]^{-1} \hat{\theta}_F \sim \chi^2_{k-g}$$

where $\hat{\theta}_F = [\theta_{g+1}, \dots, \theta_k]$, but for $H_0: \theta_j = 0$, W simplifies to:

$$t = \frac{\hat{\theta}_j}{\hat{\sigma}_{\hat{\theta}_j}} \sim N(0,1)$$

- Available in most econometric packages
- Only the full model needs to be estimated

GMM hypothesis testing

Particular case: ML

- Score/LM test:

$$\text{Score} = \nabla_{\theta} LL(X\theta) \Big|_{\theta=\hat{\theta}_R} [\text{Var}(\theta)]^{-1} \nabla_{\theta} LL(X\theta) \Big|_{\theta=\hat{\theta}_R} \sim \chi_{k-g}^2$$

- Only the restricted model needs to be estimated, which may be an advantage when the full model is complex and hard to estimate
- Rarely available in econometric packages, requiring programming

GMM hypothesis testing

2. Overidentification tests

The J test of Hansen (1982) checks whether all the moment conditions are satisfied in the data

$$H_0: E[g(z, \theta)] = 0$$

$$H_1: E[g(z, \theta)] \neq 0$$

$$J = nQ_n(\hat{\theta}) \sim \chi^2_{S-k}$$

GMM hypothesis testing

2. Overidentification tests

Eichenbaum, Hansen e Singleton (1988) proposed an extension to check the validity of a subset of moment conditions. Partition the vector of moment conditions as $g(z, \theta)' = [g_1(z, \theta)', g_2(z, \theta)']$ and suppose that the aim is testing the validity of the last s_2 moment conditions:

$$H_0: E[g_2(z, \theta)] = 0$$

$$H_1: E[g_2(z, \theta)] \neq 0$$

In addition to θ also θ_1 is estimated (from $g_1(z, \theta)$) and the test statistics is

$$J_2 = n[Q_n(\hat{\theta}) - Q_n(\hat{\theta}_1)] \sim \chi^2_{S_2}$$

GMM hypothesis testing

3. Conditional moment tests

Independently proposed by Newey (1985) and Tauchen (1985), checks whether a subset of moment conditions is satisfied, similarly to J_2 :

$$H_0: E[g_2(z, \theta)] = 0$$

$$H_1: E[g_2(z, \theta)] \neq 0$$

However, in this framework only the restricted model, based on $g_1(z, \theta)$, is estimated. The test statistic is

$$CM = n \hat{g}'_{2n} \left(\hat{\theta}_1 \right) \left(\hat{D}_n \hat{B}_n \hat{D}'_n \right) \hat{g}_{2n} \left(\hat{\theta}_1 \right) \sim \chi^2_{(s_2)}$$

where $D = -A_2 \left(A'_1 B_{11}^{-1} A_1 \right)^{-1} A'_1 B_{11}^{-1} I_{s_2}$

GMM hypothesis testing

4. Hausman test

Consider two estimators $\hat{\theta}$ and $\tilde{\theta}$. Under H_0 both are consistent but $\tilde{\theta}$ is more efficient. Under H_1 only $\hat{\theta}$ is consistent.

$$H_0: \text{plim}(\hat{\theta} - \tilde{\theta}) = 0$$

$$H_1: \text{plim}(\hat{\theta} - \tilde{\theta}) \neq 0$$

$$H = \frac{1}{n} (\hat{\theta} - \tilde{\theta})' [V(\hat{\theta}) - V(\tilde{\theta})] (\hat{\theta} - \tilde{\theta}) \sim \chi^2_{\text{rank}[V(\hat{\theta}) - V(\tilde{\theta})]}$$