

# Stochastic Calculus - Part 9

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Stochastic Differential Equations - Motivation

## Stochastic Differential Equations

- Deterministic ordinary differential equations (ODE's)

$$f(t, x(t), x'(t), x''(t), \dots) = 0, \quad 0 \leq t \leq T.$$

- ODE of order 1:

$$\frac{dx(t)}{dt} = b(t, x(t))$$

or

$$dx(t) = b(t, x(t)) dt$$

- Discrete version

$$\Delta x(t) = x(t + \Delta t) - x(t) \approx b(t, x(t)) \Delta t$$

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- Example

$$\frac{dx(t)}{dt} = cx(t)$$

has solution

$$x(t) = x(0) e^{ct}.$$

## Stochastic differential equation

- SDE in differential form:

$$\begin{aligned} dX_t &= b(t, X_t) dt + \sigma(t, X_t) dB_t, \\ X_0 &= X_0 \end{aligned} \quad (1)$$

- $b(t, X_t)$  is called the drift coefficient,  $\sigma(t, X_t)$  is called the diffusion coefficient.
- SDE in integral form

$$X_t = X_0 + \int_0^t b(s, X_s) ds + \int_0^t \sigma(s, X_s) dB_s. \quad (2)$$

- "Naif" interpretation of SDE solution:  
 $\Delta X_t \approx b(t, X_t) \Delta t + \sigma(t, X_t) \Delta B_t$ . and  
 $\Delta X_t \approx N\left(b(t, X_t) \Delta t, (\sigma(t, X_t))^2 \Delta t\right)$ .

## Definition

A solution of SDE (1) or (2) is a stochastic process  $\{X_t\}$  that satisfies:

- ①  $\{X_t\}$  is an adapted process with continuous trajectories
- ②  $\mathbb{E} \left[ \int_0^T (\sigma(s, X_s))^2 ds \right] < \infty$ .
- ③  $\{X_t\}$  satisfies SDE (1) or (2)

- The solutions of SDE's are also called "diffusions" or "diffusion processes".

Stochastic Differential Equations: Some examples

## Use of Itô formula to solve an SDE

- **Example:** Geometric Brownian motion (gBm). SDE:

$$dX_t = \mu X_t dt + \sigma X_t dB_t \quad (3)$$

or

$$X_t = X_0 + \mu \int_0^t X_s ds + \sigma \int_0^t X_s dB_s \quad (4)$$

- How to solve this SDE?
- Assume that  $X_t = f(t, B_t)$  with  $f \in C^{1,2}$ . By Itô formula:

$$X_t = f(t, B_t) = X_0 + \int_0^t \left( \frac{\partial f}{\partial t}(s, B_s) + \frac{1}{2} \frac{\partial^2 f}{\partial x^2}(s, B_s) \right) ds + \int_0^t \frac{\partial f}{\partial x}(s, B_s) dB_s. \quad (5)$$

- Comparing (4) and (5) we have that (there is uniqueness of representation as an Itô process)

$$\frac{\partial f}{\partial s}(s, B_s) + \frac{1}{2} \frac{\partial^2 f}{\partial x^2}(s, B_s) = \mu f(s, B_s), \quad (6)$$

$$\frac{\partial f}{\partial x}(s, B_s) = \sigma f(s, B_s). \quad (7)$$

- Differentiating (7), we obtain

$$\frac{\partial^2 f}{\partial x^2}(s, x) = \sigma \frac{\partial f}{\partial x}(s, x) = \sigma^2 f(s, x)$$

and replacing in (6), we get

$$\left(\mu - \frac{1}{2}\sigma^2\right) f(s, x) = \frac{\partial f}{\partial s}(s, x)$$

- Separating the variables:  $f(s, x) = g(s)h(x)$ , we have

$$\frac{\partial f}{\partial s}(s, x) = g'(s)h(x)$$

and

$$g'(s) = \left(\mu - \frac{1}{2}\sigma^2\right) g(s)$$

which is a linear EDO with solution

$$g(s) = g(0) \exp\left[\left(\mu - \frac{1}{2}\sigma^2\right) s\right]$$

- Using (7), we have  $h'(x) = \sigma h(x)$ . Hence

$$f(s, x) = f(0, 0) \exp\left[\left(\mu - \frac{1}{2}\sigma^2\right) s + \sigma x\right].$$

- Conclusion:

$$X_t = f(t, B_t) = X_0 \exp \left[ \left( \mu - \frac{1}{2} \sigma^2 \right) t + \sigma B_t \right] \quad (8)$$

which is a geometric Brownian motion (gBm).

- Remark: Note that we have obtained the solution of an SDE by solving a deterministic PDE (partial differential equation).

- Let us confirm that (8) satisfies the SDE (3) or (4).
- Applying the Itô formula to  $X_t = f(t, B_t)$ , with

$$f(t, x) = X_0 \exp \left[ \left( \mu - \frac{1}{2} \sigma^2 \right) t + \sigma x \right],$$

we obtain

$$\begin{aligned} X_t &= X_0 + \int_0^t \left[ \left( \mu - \frac{1}{2} \sigma^2 \right) X_s + \frac{1}{2} \sigma^2 X_s \right] ds + \int_0^t \sigma X_s dB_s \\ &= X_0 + \mu \int_0^t X_s ds + \sigma \int_0^t X_s dB_s \end{aligned}$$

- or

$$dX_t = \mu X_t dt + \sigma X_t dB_t.$$

- **Example:** Ornstein-Uhlenbeck process (or Langevin equation):

$$dX_t = \mu X_t dt + \sigma dB_t.$$

or

$$X_t = X_0 + \mu \int_0^t X_s ds + \sigma \int_0^t dB_s.$$

- Remark: in the discret form we would have

$$X_{t+1} = (1 + \mu) X_t + \sigma (B_{t+1} - B_t)$$

or

$$X_{t+1} = \phi X_t + Z_t,$$

with  $\phi = 1 + \mu$  and  $Z_t \sim N(0, \sigma^2)$ . This is an autoregressive time series of order 1.

- **Example:** Ornstein-Uhlenbeck process (or Langevin equation) - cont.
- Let

$$Y_t = e^{-\mu t} X_t$$

or  $Y_t = f(t, X_t)$ , with  $f(t, x) = e^{-\mu t} x$ . By Itô formula,

$$Y_t = Y_0 + \int_0^t \left( -\mu e^{-\mu s} X_s + \frac{1}{2} \sigma^2 \times 0 \right) ds + \int_0^t \sigma e^{-\mu s} dB_s.$$

- Hence,

$$X_t = e^{\mu t} X_0 + e^{\mu t} \int_0^t \sigma e^{-\mu s} dB_s.$$

- If  $X_0 = \text{cte.}$ , this process is called an Ornstein-Uhlenbeck process.

- **Example:** The geometric Brownian motion (again)

- Let

$$dX_t = \mu X_t dt + \sigma X_t dB_t \quad (9)$$

or

$$X_t = X_0 + \mu \int_0^t X_s ds + \sigma \int_0^t X_s dB_s. \quad (10)$$

- Assumption

$$X_t = e^{Z_t}.$$

or

$$Z_t = \ln(X_t).$$

- Applying the Itô formula to  $f(X_t) = \ln(X_t)$ , we get

$$\begin{aligned} dZ_t &= \frac{1}{X_t} dX_t + \frac{1}{2} \left( \frac{-1}{X_t^2} \right) (dX_t)^2 \\ &= \left( \mu - \frac{1}{2} \sigma^2 \right) dt + \sigma dB_t. \end{aligned}$$

- That is

$$Z_t = Z_0 + \left( \mu - \frac{1}{2} \sigma^2 \right) t + \sigma B_t$$

- and

$$X_t = X_0 \exp \left[ \left( \mu - \frac{1}{2} \sigma^2 \right) t + \sigma B_t \right].$$

- By the same procedure, one can show that the linear homogeneous equation

$$dX_t = b(t) X_t dt + \sigma(t) X_t dB_t$$

has the solution

$$X_t = X_0 \exp \left[ \int_0^t \left( b(s) - \frac{1}{2} \sigma(s)^2 \right) ds + \int_0^t \sigma(s) dB_s \right].$$

## Exercise

- Exercise: Solve the SDE

$$dX_t = a(m - X_t) dt + \sigma dB_t,$$

$$X_0 = x,$$

where  $a, \sigma > 0$  and  $m \in \mathbb{R}$ . Calculate also the mean and variance of  $X_t$  when  $t \rightarrow \infty$  and find the distribution of  $X_t$  when  $t \rightarrow \infty$  (invariant or stationary distribution).