

# Models in Finance - Lecture 3

## Master in Actuarial Science

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# Stochastic integrals

- Motivation : Consider a “differential equation” with “noise” of type:

$$\frac{dX}{dt} = b(t, X_t) + \sigma(t, X_t) \frac{dB_t}{dt}.$$

- “ $\frac{dB_t}{dt}$ ” is a stochastic “noise”.  
Does not exist in classical sense since  $B$  is not differentiable.
- “Stochastic differential equation” (SDE) in integral form :

$$X_t = X_0 + \int_0^t b(s, X_s) ds + \int_0^t \sigma(s, X_s) dB_s \quad (1)$$

- How to define the integral:

$$\int_0^T u_s dB_s \quad ? \quad (2)$$

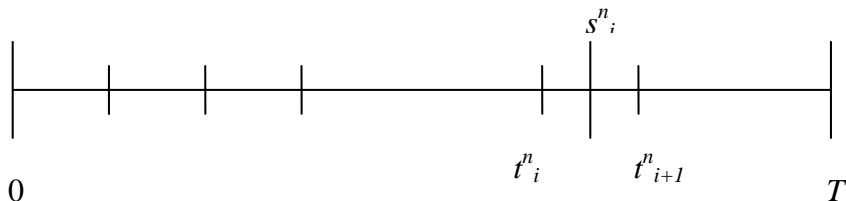
where  $B$  is a Brownian motion and  $u$  is an appropriate adapted process.

- First strategy: Consider the integral (2)
- Consider a sequence of partitions of  $[0, T]$  and a sequence of points:

$$\tau_n: 0 = t_0^n < t_1^n < t_2^n < \dots < t_{k(n)}^n = T$$

$$s_n: t_i^n \leq s_i^n \leq t_{i+1}^n, \quad i = 0, \dots, k(n) - 1,$$

such that  $\limsup_{n \rightarrow \infty} \max_i (t_{i+1}^n - t_i^n) = 0$ .



Riemann-Stieltjes (R-S) integral:

$$\int_0^T f dg := \lim_{n \rightarrow \infty} \sum_{i=0}^{n-1} f(s_i^n) \Delta g_i,$$

where  $\Delta g_i := g(t_{i+1}^n) - g(t_i^n)$ , if the limit exists and is independent of the sequences  $\tau_n$  and  $s_n$ .

- If  $g$  is a differentiable function and  $f$  is continuous the (R-S) integral is well defined:  $\int_0^T f(t) dg(t) = \int_0^T f(t) g'(t) dt$ .
- In the Bm case  $B$ , it is clear that  $B'(t)$  does not exist, so we cannot define the path integral:

$$\int_0^T u_t(\omega) dB_t(\omega) \not\stackrel{\times}{=} \int_0^T u_t(\omega) B'_t(\omega) dt$$

- Problem: The integral  $\int_0^T B_t(\omega) dB_t(\omega)$  does not exist as a R-S integral.  
How to define the integral (2)?

- We will construct the stochastic integral  $\int_0^T u_t dB_t$  using a probabilistic approach.

## Definition

Consider processes  $u$  of class  $L^2_{a,T}$ , which is defined as the class of processes  $u = \{u_t, t \in [0, T]\}$ , such that:

- 1  $u$  is adapted and measurable.
- 2  $E \left[ \int_0^T u_t^2 dt \right] < \infty$ .

- Condition 2. allows us to show that  $u$  as a map of two variables  $t$  and  $\omega$  belongs to the space  $L^2([0, T] \times \Omega)$  and that:

$$E \left[ \int_0^T u_t^2 dt \right] = \int_0^T E [u_t^2] dt.$$

- idea: we will define  $\int_0^T u_t dB_t$  for  $u \in L^2_{a,T}$  as a limit in mean-square (i.e., a limit in  $L^2(\Omega)$ ) of integrals of simple processes.

# Stochastic Itô integral for simple processes

## Definition

$u \in \mathcal{S}$  (set of simple processes in  $[0, T]$ ) is called a simple process if

$$u_t = \sum_{j=1}^n \phi_j 1_{(t_{j-1}, t_j]}(t), \quad (3)$$

where  $0 = t_0 < t_1 < \dots < t_n = T$ , and the r.v.  $\phi_j$  are square-integrables ( $E[\phi_j^2] < \infty$ ) and  $\mathcal{F}_{t_{j-1}}$ -measurable

## Definition

If  $u$  is a simple process of form (3) ( $u \in \mathcal{S}$ ) then the stochastic Itô integral of  $u$  with respect to Bm  $B$  is:

$$\int_0^T u_t dB_t := \sum_{j=1}^n \phi_j (B_{t_j} - B_{t_{j-1}}).$$



## Example

Consider the simple process

$$u_t = \sum_{j=1}^n B_{t_{j-1}} \mathbf{1}_{(t_{j-1}, t_j]}(t).$$

Then

$$\int_0^T u_t dB_t = \sum_{j=1}^n B_{t_{j-1}} (B_{t_j} - B_{t_{j-1}}).$$

Then (why?)

$$\begin{aligned} E \left[ \int_0^T u_t dB_t \right] &= \sum_{j=1}^n E [B_{t_{j-1}} (B_{t_j} - B_{t_{j-1}})] \\ &= \sum_{j=1}^n E [B_{t_{j-1}}] E [B_{t_j} - B_{t_{j-1}}] = 0. \end{aligned}$$

**Proposition:** (Isometry property or norm preservation property). Let  $u \in \mathcal{S}$ .

Then:

$$E \left[ \left( \int_0^T u_t dB_t \right)^2 \right] = E \left[ \int_0^T u_t^2 dt \right] = \int_0^T E [u_t^2] dt. \quad (4)$$

**Proof.**

With  $\Delta B_j := B_{t_j} - B_{t_{j-1}}$ , we have (Exercise (homework): justify all the steps in this proof):

$$\begin{aligned} E \left[ \left( \int_0^T u_t dB_t \right)^2 \right] &= E \left[ \left( \sum_{j=1}^n \phi_j \Delta B_j \right)^2 \right] \\ &= \sum_{j=1}^n E \left[ \phi_j^2 (\Delta B_j)^2 \right] + 2 \sum_{i < j} E \left[ \phi_i \phi_j \Delta B_i \Delta B_j \right]. \end{aligned}$$



## Proof.

(cont.) Note that since  $\phi_i \phi_j \Delta B_i$  is  $\mathcal{F}_{j-1}$ -measurable and  $\Delta B_j$  is independent of  $\mathcal{F}_{j-1}$ , then

$$\sum_{i < j}^n E [\phi_i \phi_j \Delta B_i \Delta B_j] = \sum_{i < j}^n E [\phi_i \phi_j \Delta B_i] E [\Delta B_j] = 0.$$

On the other hand, since  $\phi_j^2$  is  $\mathcal{F}_{j-1}$ -measurable and  $\Delta B_j$  is independent of  $\mathcal{F}_{j-1}$ ,

$$\begin{aligned} \sum_{j=1}^n E [\phi_j^2 (\Delta B_j)^2] &= \sum_{j=1}^n E [\phi_j^2] E [(\Delta B_j)^2] \\ &= \sum_{j=1}^n E [\phi_j^2] (t_j - t_{j-1}) = \\ &= E \left[ \int_0^T u_t^2 dt \right]. \end{aligned}$$

- Other properties of  $\int_0^T u_t dB_t$  for  $u \in \mathcal{S}$ :

- 1 Linearity: If  $u, v \in \mathcal{S}$ :

$$\int_0^T (au_t + bv_t) dB_t = a \int_0^T u_t dB_t + b \int_0^T v_t dB_t. \quad (5)$$

- 2 Zero mean:

$$E \left[ \int_0^T u_t dB_t \right] = 0. \quad (6)$$

Exercise: Prove the property 2.

Exercise: Compute  $\int_0^5 f(s) dB_s$  with  $f(s) = 1$  if  $0 \leq s \leq 2$  and  $f(s) = 4$  if  $2 < s \leq 5$  and what is the distribution of the resulting r.v.?

# Ito integral

## Lemma

If  $u \in L^2_{a,T}$  then exists a sequence of simple processes  $\{u^{(n)}\}$  such that

$$\lim_{n \rightarrow \infty} E \left[ \int_0^T |u_t - u_t^{(n)}|^2 dt \right] = 0. \quad (7)$$

Proof: see the book of Oksendal or the Nualart notes.

## Definition

The Itô stochastic integral of  $u \in L^2_{a,T}$  is defined as the limit (in the  $L^2(\Omega)$  sense):

$$\int_0^T u_t dB_t = \lim_{n \rightarrow \infty} (L^2) \int_0^T u_t^{(n)} dB_t, \quad (8)$$

where  $\{u^{(n)}\}$  is a sequence of simple processes satisfying (7).

# Properties of the Itô integral

- Properties of the Itô integral  $\int_0^T u_t dB_t$  for  $u \in L^2_{a,T}$ .

- 1 Isometry (or norm preservation) and product rule:

$$E \left[ \left( \int_0^T u_t dB_t \right)^2 \right] = E \left[ \int_0^T u_t^2 dt \right] = \int_0^T E \left[ u_t^2 \right] dt. \quad (9)$$

$$E \left[ \left( \int_0^T u_t dB_t \right) \left( \int_0^T v_t dB_t \right) \right] = \int_0^T E \left[ u_t v_t \right] dt. \quad (10)$$

- 2 Zero mean:

$$E \left[ \int_0^T u_t dB_t \right] = 0 \quad (11)$$

- 3 Linearity:

$$\int_0^T (a u_t + b v_t) dB_t = a \int_0^T u_t dB_t + b \int_0^T v_t dB_t. \quad (12)$$

- 4 The process  $\left\{ \int_0^t u_s dB_s, t \geq 0 \right\}$  is a martingale.

- 5 The sample paths of  $\left\{ \int_0^t u_s dB_s, t \geq 0 \right\}$  are continuous.

## Example

Let us show that

$$\int_0^T B_t dB_t = \frac{1}{2} B_T^2 - \frac{1}{2} T.$$

Since  $u_t = B_t$ , let us consider the sequence of simple processes

$$u_t^n = \sum_{j=1}^n B_{t_{j-1}^n} 1_{(t_{j-1}^n, t_j^n]}(t),$$

with  $t_j^n := \frac{j}{n} T$ .

## Example

(cont.)

$$\begin{aligned}\int_0^T B_t dB_t &= \lim_{n \rightarrow \infty} (L^2) \int_0^T u_t^{(n)} dB_t = \\ &= \lim_{n \rightarrow \infty} (L^2) \sum_{j=1}^n B_{t_{j-1}^n} (B_{t_j^n} - B_{t_{j-1}^n}) \\ &= \lim_{n \rightarrow \infty} (L^2) \frac{1}{2} \sum_{j=1}^n \left[ (B_{t_j^n}^2 - B_{t_{j-1}^n}^2) - (B_{t_j^n} - B_{t_{j-1}^n})^2 \right] \\ &= \frac{1}{2} (B_T^2 - T),\end{aligned}$$

where we used:  $E \left[ \left( \sum_{j=1}^n (\Delta B_{t_j^n})^2 - T \right)^2 \right] = 0$  and

$$\frac{1}{2} \sum_{j=1}^n (B_{t_j^n}^2 - B_{t_{j-1}^n}^2) = \frac{1}{2} B_T^2.$$



- Let us prove that  $E \left[ \left( \sum_{j=1}^n (\Delta B_{t_j^n})^2 - T \right)^2 \right] = 0$ .

Using the independence of increments and  $E \left[ (\Delta B_{t_j^n})^2 \right] = \Delta t_j^n$ , then

$$\begin{aligned} E \left[ \left( \sum_{j=1}^n (\Delta B_{t_j^n})^2 - T \right)^2 \right] &= E \left[ \left( \sum_{j=1}^n \left[ (\Delta B_{t_j^n})^2 - \Delta t_j^n \right] \right)^2 \right] \\ &= \sum_{j=1}^n E \left[ (\Delta B_{t_j^n})^2 - \Delta t_j^n \right]^2. \end{aligned}$$

Using the fact that  $E \left[ (B_t - B_s)^{2k} \right] = \frac{(2k)!}{2^k \cdot k!} (t - s)^k$ , then

$$\begin{aligned} E \left[ \left( \sum_{j=1}^n (\Delta B_{t_j^n})^2 - T \right)^2 \right] &= \sum_{j=1}^n \left[ 3 (\Delta t_j^n)^2 - 2 (\Delta t_j^n)^2 + (\Delta t_j^n)^2 \right] \\ &= 2 \sum_{j=1}^n (\Delta t_j^n)^2 = 2T \sup_j |\Delta t_j^n| \xrightarrow{n \rightarrow \infty} 0. \end{aligned}$$

- Note: By formula  $E \left[ (B_t - B_s)^{2k} \right] = \frac{(2k)!}{2^k \cdot k!} (t - s)^k$  we have that

$$\begin{aligned} \text{Var} \left[ (\Delta B)^2 \right] &= E \left[ (\Delta B)^4 \right] - \left( E \left[ (\Delta B)^2 \right] \right)^2 \\ &= 3 (\Delta t)^2 - (\Delta t)^2 = 2 (\Delta t)^2. \end{aligned}$$

We also know that

$$E \left[ (\Delta B)^2 \right] = \Delta t.$$

Therefore, if  $\Delta t$  is small, the variance of  $(\Delta B)^2$  is very small when compared with its expected value

$\implies$  therefore when  $\Delta t \rightarrow 0$  or “ $\Delta t = dt$ ”, we have:

$$(dB_t)^2 \approx dt. \tag{13}$$